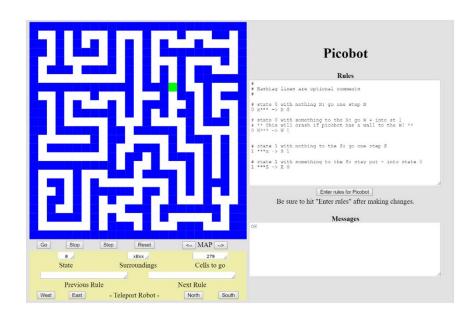
```
do1()
do2()
```

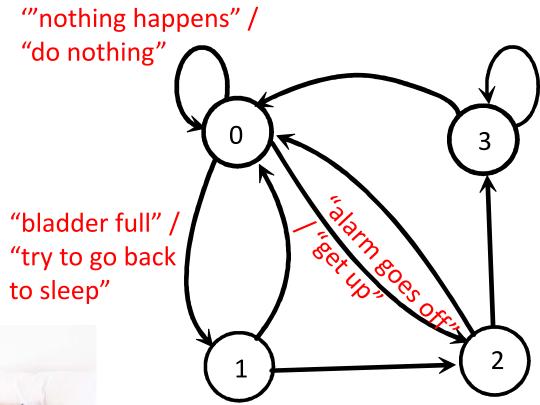
Finite State Machines (FSM)

Picobot





Finite State Machine (FSM)



State 0: "in bed, asleep"

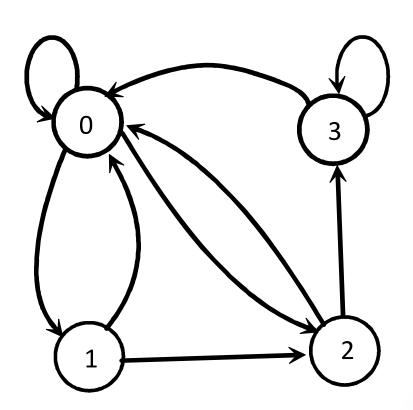
State 1: "in bed, awake"

State 2: "in the bedroom, out of bed"

Finite State Machine (FSM)

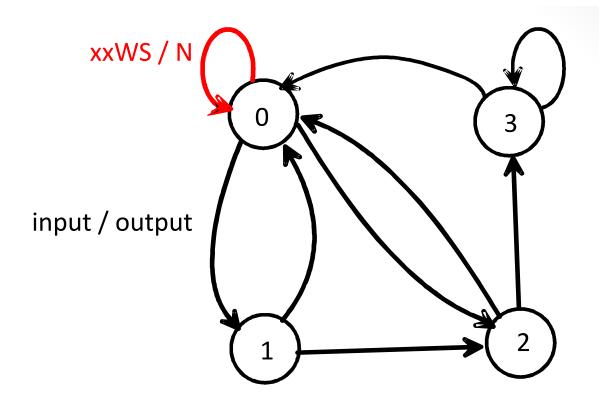


Mealy FSM



state input → output

new state



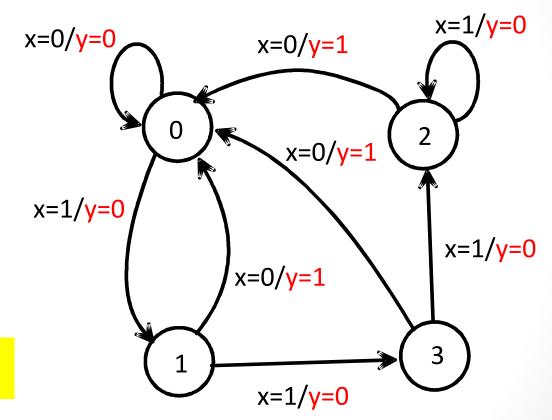
state	surroundings		direction	new state
0	xx WS	→	Ν	0

Finite State Machine (FSM)

State: s

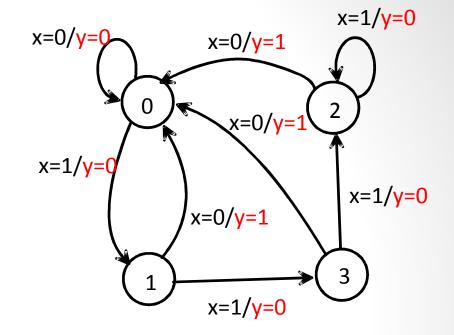
Input: x

Output: y



Mealy FSM

```
if (state == 0):
  if (x == 0):
      y = 0
      next_state = 0
  elif (x == 1):
      y = 0
      next_state = 1
elif (state == 1):
  if (x == 0):
      y = 1
      next_state = 0
  elif (x == 1):
      y = 0
      next_state = 3
```



Mealy FSM

•••

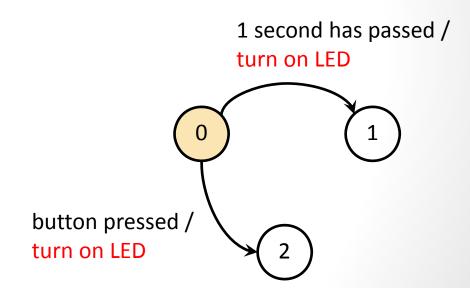
state = next_state

Complete the FSM ...



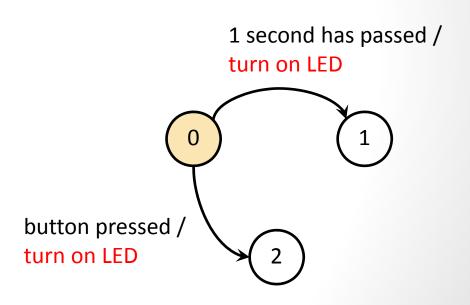


 $\binom{2}{2}$



```
if (state == 0):
    if (x == 0):
        y = 0
        next_state = 0
    elif (x == 1):
        y = 0
        next_state = 1

...
state = next state
```



```
if (state == 0):
    time.sleep(1)
    if (read_button() == PRESSED):
        turn_on_LED()
        next_state = 2
    else:
        turn_on_LED()
        next_state = 1
    button pressed /
    turn on LED
...
```

functionality?

A. Yes B. No

state = next state

Does this implement the desired

This code is blocking!

```
if (state == 0):
    time.sleep(1)
    if (read_button() == PRESSED):
        turn_on_LED()
        next_state = 2
    else:
        turn_on_LED()
        next_state = 1
    button pressed/
    turn on LED
...
```

state = next_state

How can we implement the desired functionality?

Go through FSM as fast as possible ...

```
if (state == 0):
    if (read_button() == PRESSED):
        turn_on_LED()
        next_state = 2
elif (now-last_transition > 1):
        turn_on_LED()
        next_state = 1
else:
    next_state = 0
button pressed/
turn on LED
```